EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	4784	load with balanc$4 and status and tracking	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:24
S2	478	load with balanc$4 and status and tracking and (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:24
S3	172	load with balanc$4 and status same (position$4 or movement$4) and tracking and (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:25
S4	148	load with balanc$4 and status and tracking same (position$4 or movement$4) and (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:25
S5	16	load with balanc$4 and status and tracking same (position$4 or movement$4) and (conveyor or robot$4) and "700"/$.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:27
S6	35	load with balanc$4 same (position$4 or movement$4) and (conveyor or robot$4) and "700"/$.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:32
S7	39	load adj balanc$4 and (position$4 or movement$4) same (conveyor or robot$4) and "700"/$.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:43

S8	34	load adj balanc$4 and (position$4 or movement$4) same (conveyor or robot$4) and "700"/$.ccls. not S6	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:43
S9	195	load adj balanc$4 and (position$4 or movement$4) same (conveyor or robot$4) and control$4 with (data or message)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:44
S12	14663	robot$4 with control with system	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:46
S13	2514	robot$4 with control with system and (stor$4) and (status or message)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:47
S14	1264	robot$4 with control with system and (stor$4) and (status or message) and control with signal	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:47
S15	657	robot$4 with control with system and (stor$4) and (status) with (data or signal or message or information) and control with signal	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:48
S16	1123	robot$4 with control with system and (stor$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:48

S17	325	robot$4 with control with system and (stor $4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and "700"/$.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:48
S18	360	robot$4 with control with system and (stor $4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and ("700"/$.ccls. or "901"/$.ccls.)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:50
S19	48	robot$4 with control with system.ab. and (stor$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and ("700"/$.ccls. or "901"/$.ccls.)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:50
S21	0	robot$4 with control with system.ab. and (stor$4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:58
S22	71	robot$4 with control with system and (stor $4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 20:58

S23	5	robot$4 with control with system and (stor $4) and (status) with (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc$4 with (device or machine or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:07
S24	10	robot$4 with control with system and (stor $4) and (data or signal or message or information or datum) and control with (data or signal or message or information) and load adj balanc$4 with (device or machine or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:09
S25	10	robot$4 with control with system and (stor $4) and control with (data or signal or message or information or datum) and load adj balanc$4 with (device or machine or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:09
S26	4	robot$4 with control with system and (stor $4) and control with (data or signal or message or information or datum) and load adj balanc$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:09

S27	5	(conveyor or robot$4) same control with system and (stor$4) and control with (data or signal or message or information or datum) and load adj balanc$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:10
S28	4	(conveyor or robot$4) same control with position$4 and control with (data or signal or message or information or datum) and load adj balanc$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:11
S29	14	(conveyor or robot$4) same position$4 and control with (data or signal or message or information or datum) and load adj balanc$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:12
S30	23	(conveyor or robot$4) same position$4 and load adj balanc$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:14
S31	121	(conveyor or robot$4) and load adj balanc$4 with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:15
S38	63	load adj balanc$4 same (equipment or devices or machines or components) and (conveyor or robot$4) with control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:30

S39	242	load adj balanc$4 and (equipment or devices or machines or components) and (conveyor or robot$4) with control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:31
S40	169	load adj balanc$4 with (equipment or devices or machines or components) and (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:33
S41	121	load adj balanc$4 with (equipment or devices or machines) and (conveyor or robot $4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:33
S42	231	load adj balanc$4 and (semiconductor or wafer or rectile or lithograph) and position$4 and (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:37
S43	94	load adj balanc$4 and (semiconductor or wafer or rectile or lithograph) and position$4 same (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:37
S44	94	load adj balanc$4 and (semiconductor or wafer or rectile or lithograph) and position$4 same (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:37
S45	13	line adj balanc$4 and (semiconductor or wafer or rectile or lithograph) and position$4 same (conveyor or robot$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/26 21:58
S46	131	line adj balancing and position$4 with control	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:13

S47	4	line adj balancing and position$4 with control and (robots or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:14
S48	0	line adj balancing and position$4 with (robots or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:14
S49	1	line adj balancing and position$4 with (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:15
S50	9	line adj balanc$4 and position$4 with (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:15
S51	16	line adj balanc$4 and position$4 same (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:15
S52	1063	triggering and position $4 same (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:23
S53	9	(repeat$4 or continous) with triggering and position $4 same (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:24
S54	14	(repeat$4 or continuous) with triggering and position $4 same (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:24

S55	71	(repeat$4 or continuous) with (sending or triggering) with (signal or message or data or information or command) and position$4 and (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:25
S56	7	(repeat$4 or continuous) with (sending or triggering) with (signal or message or data or information or command) and position$4 and (robot or robotic) and balancing	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:25
S57	71	(repeat$4 or continuous) with (sending or triggering) with (signal or message or data or information or command) and position$4 and (robot or robotic)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 03:26
S68	13	line adj2 balancing and robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:13
S69	0	command with signal with all with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:28
S70	0	command with all with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:28
S71	0	signal with all with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:28

S72	74112	positioning with (devices or machines or equipment)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:29
S73	1630	positioning with (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:29
S74	44767	positioning with (every or all) (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:29
S75	4	positioning with (every or all) with (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:29
S76	4	positioning with (every or ""all"") with (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:30
S77	4	positioning same (every or ""all"") with (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:30
S78	62	(information or datum or command or data) same (every or ""all"") with (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:31
S79	21	(information or datum or command or data) same broadcast same (devices or machines or equipment) same robot$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:36

S81	314	conveyor and broadcast with (signal or output or input or command)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:47
S82	424	conveyor and broadcast with (signal or output or input or command or data or datum)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:47
S83	48	conveyor and broadcast with (signal or output or input or command or data or datum) with (move$4 or position$4 or placement or place$5)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:48
S84	59	(robot$4 or conveyor) and broadcast with (signal or output or input or command or data or datum) with (move$4 or position$4 or placement or place $5) same (devices or equipment or machines or components or elements)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:49
S85	31	(assembly near2 (line or system)) and broadcast with (signal or output or input or command or data or datum) with (move$4 or position$4 or placement or place$5) same (devices or equipment or machines or components or elements)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 04:59

S86	101	scheduling and broadcast with (signal or output or input or command or data or datum) with (move$4 or position$4 or placement or place$5) same (devices or equipment or machines or components or elements)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:01
S87	80	scheduling and broadcast with (signal or output or input or command or data or datum) with (move$4 or position$4 or placement or place$5) same (devices or equipment or machines)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:01
S91	343	electronic adj cam	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:31
S92	0	electronic adj cam and load adj balancing	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:31
S93	1402	broadcast with control with (machines or equipment or cam)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:33
S94	3198	broadcast with control with (machines or equipment or cam or devices)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:33
S95	453	broadcast with control with (machines or equipment or cam or devices) and index$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:33

S96	36	electronic adj cam and index$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:33
S97	171	broadcast with control with (machines or equipment or cam or devices and pick near2 pul) and index $3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:35
S98	171	broadcast with control with (machines or equipment or cam or devices and pick near2 pull) and index $3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:35
S99	0	broadcast with control with (pick near2 pull) and index$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:35
S100	0	broadcast with control with (pick near2 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:35
S101	0	broadcast with control with (pick with pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:36
S102	0	broadcast with control same (pull near2 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:36
S103	2876	control same (pull near2 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:36

S104	58	control same (pull near2 pull) and broadcast	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:36
S105	287	broadcast and robot $4 with assembl$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:38
S106	176	broadcast and robot $4 with assembl$4 and central	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:39
S107	2114	(700/245).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:56
S109	354	(700/247).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:57
S110	326	S109 and (plurality or robots)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 05:59
S111	54	S109 and (plurality with robots)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 06:29

S115	103	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 06:54
S116	77	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and ("700"/$.ccls. or "901"/$.ccls.)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 06:55
S117	21	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and ("700"/$.ccls. or "901"/$.ccls.) and (buffer$4 or index$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 06:56
S118	8	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) near2 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and adaptive with control$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 07:05

S122	332	(700/248).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 08:00
S125	46	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and sort$$	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:24
S126	46	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and sort$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:24
S127	26	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) near4 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (sort$4 or pick with pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:27

S128	0	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) near4 robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick with pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:28
S129	0	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick with pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:28
S130	0	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) with robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick near3 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:28
S131	0	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) same robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick near3 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:28

S132	0	(synchron$6 or coordinat$4 or cooperat$5) same (numerous or plurality or several) and robots and (central or primary or master) with (controller or processor or control or cpu or computer or device or component) and (pick near3 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:28
S133	550	(pick near3 pull)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:29
S134	321	(700/250).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 10:55
S135	647	(700/259).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/10/27 11:58

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